

FIG. 1

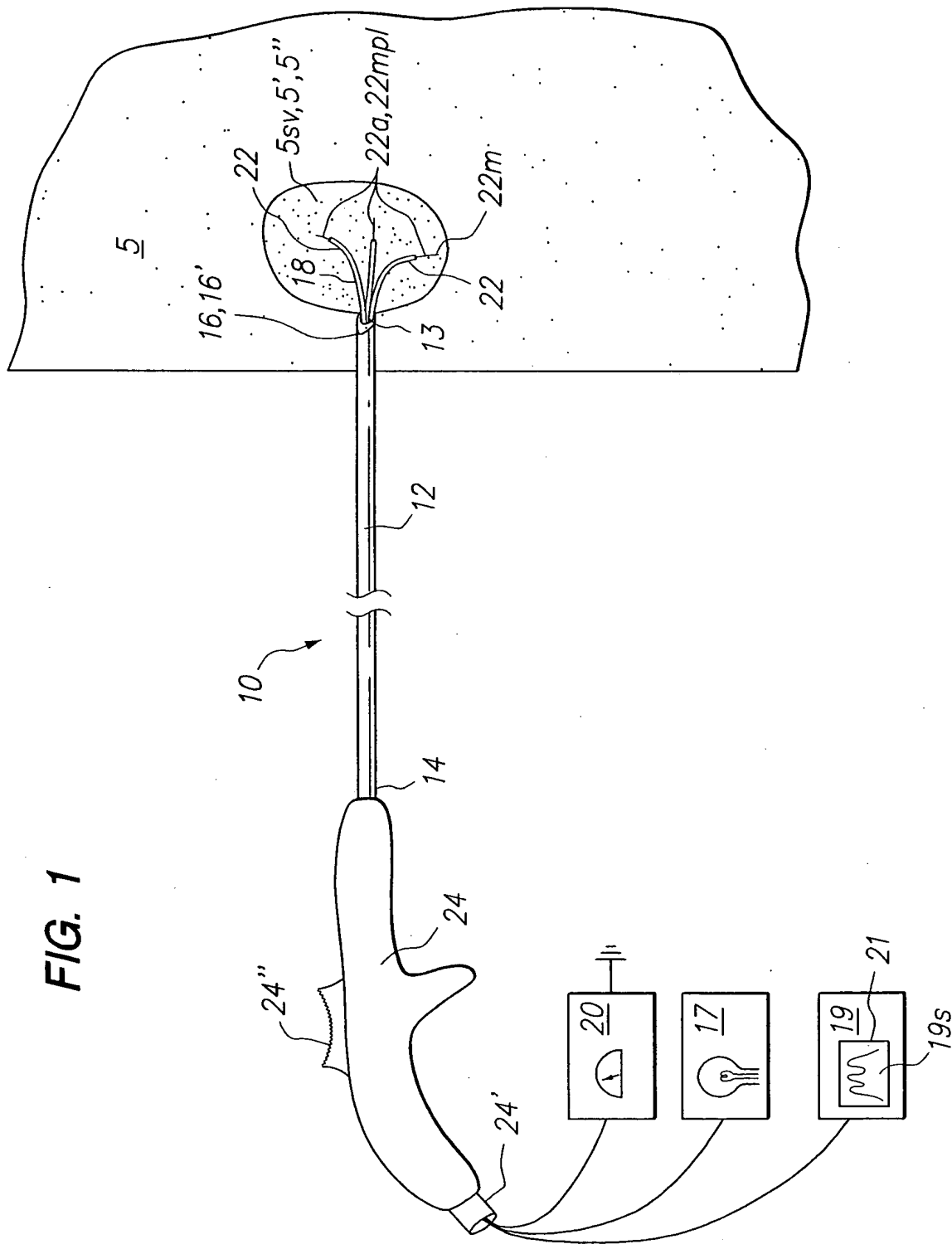


FIG. 2

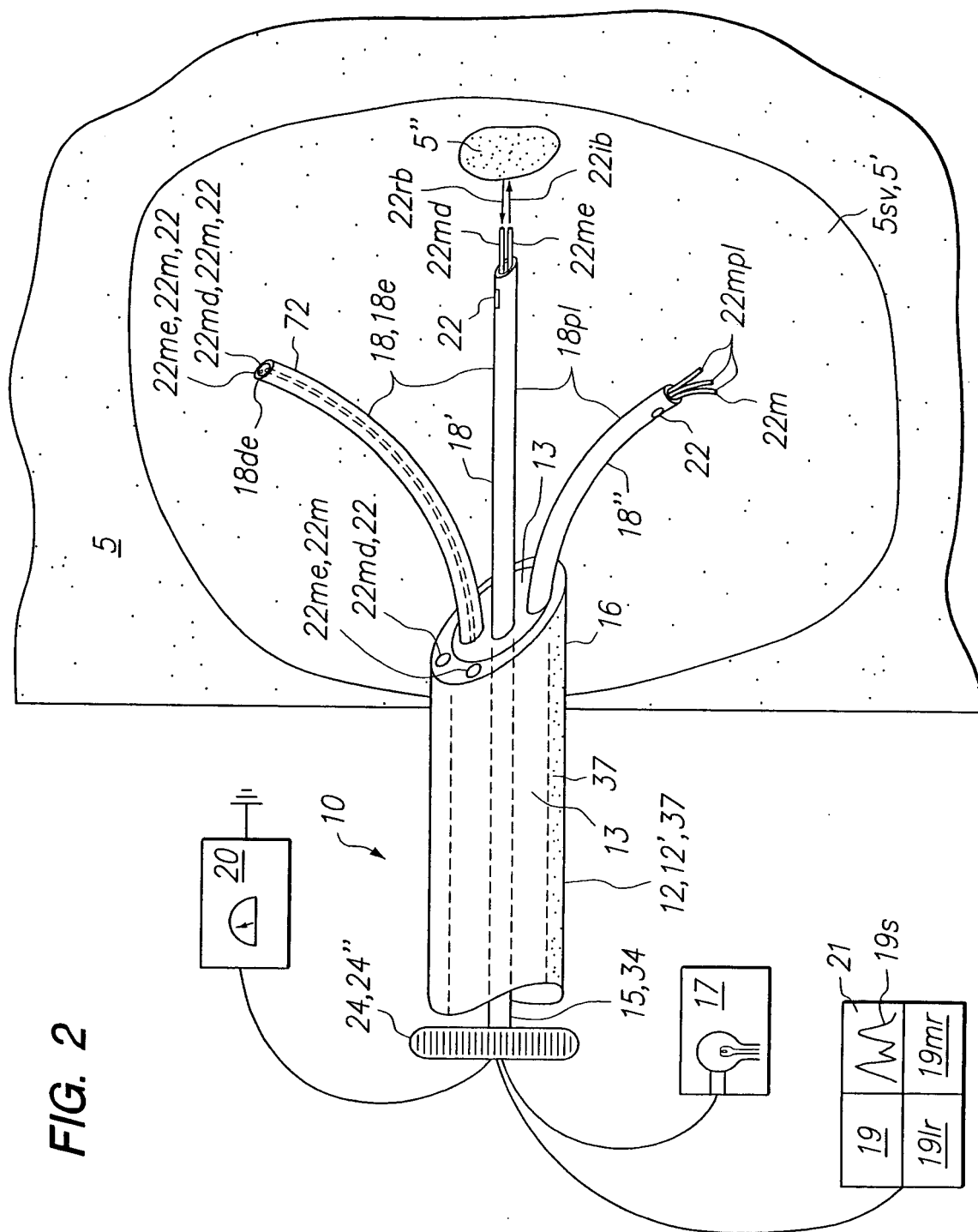


FIG. 3A

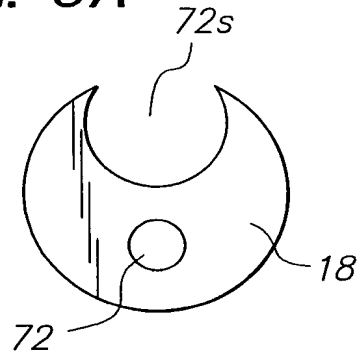


FIG. 3B

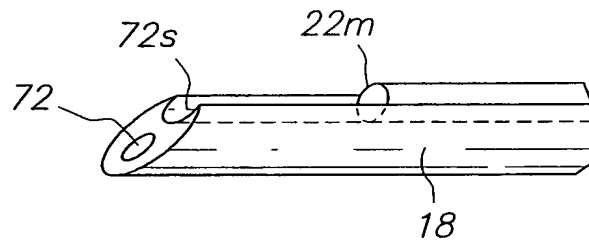


FIG. 3C

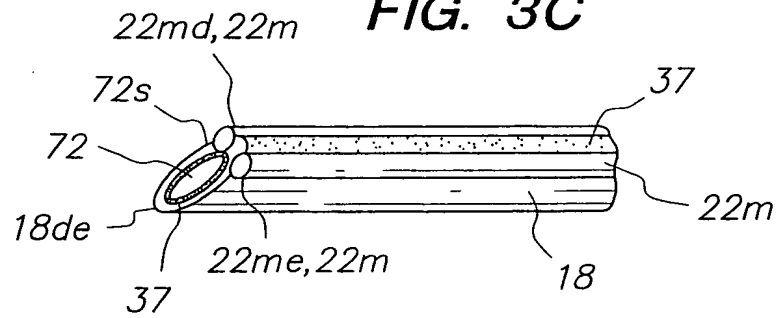


FIG. 4

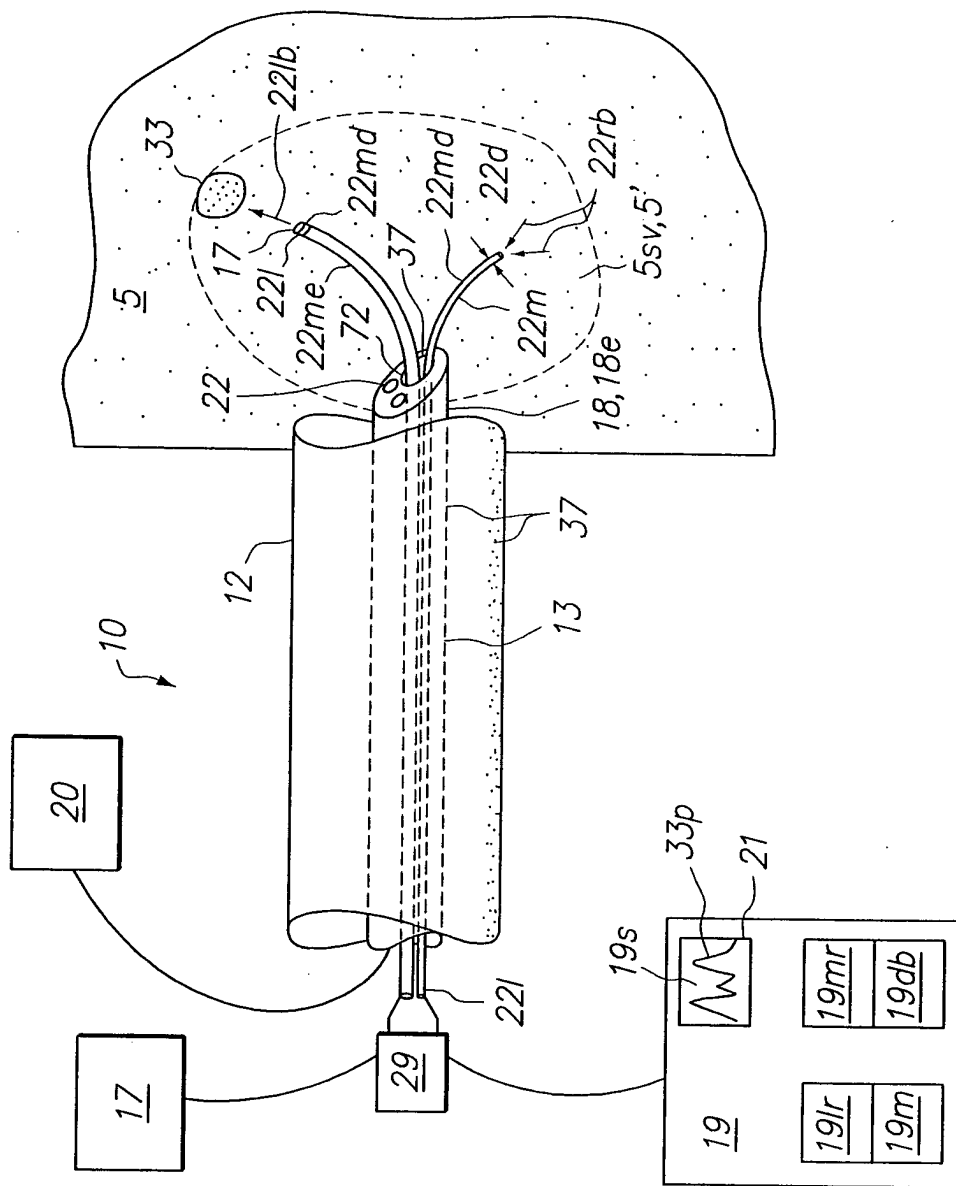


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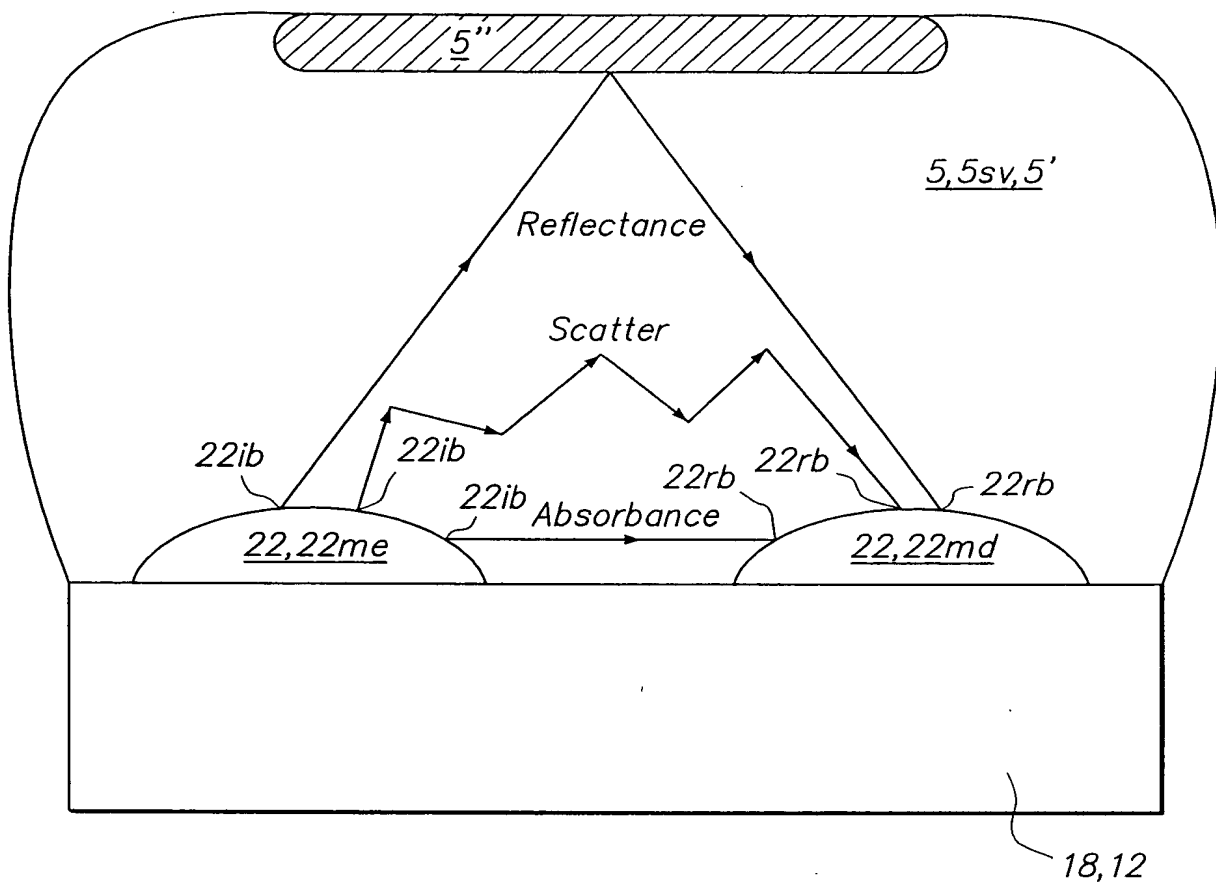


FIG. 6

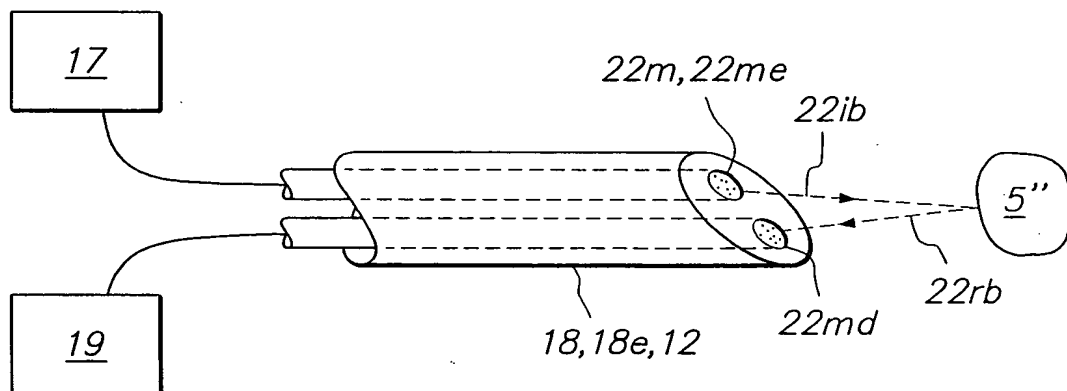


FIG. 7

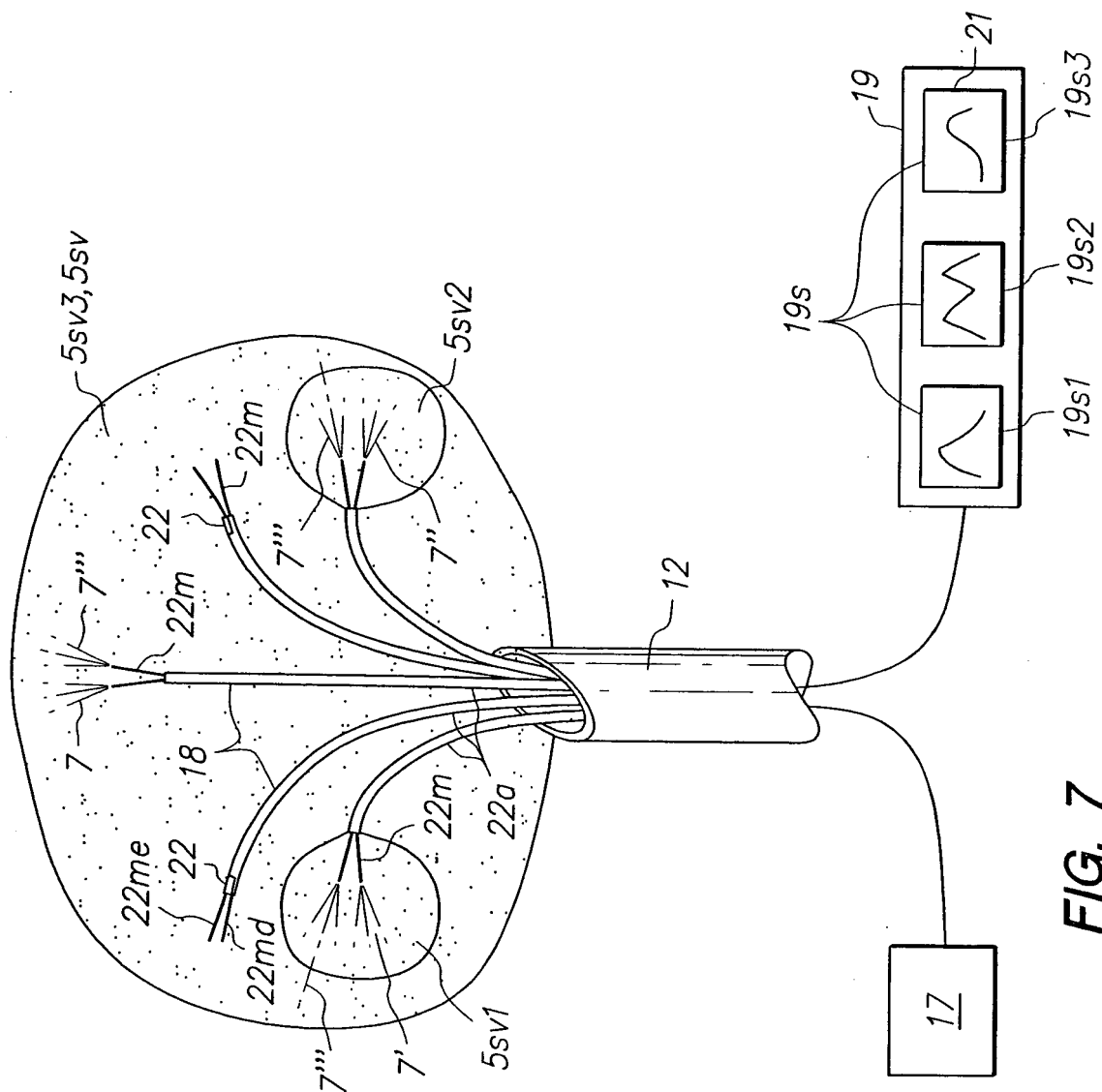


FIG. 7

FIG. 8A

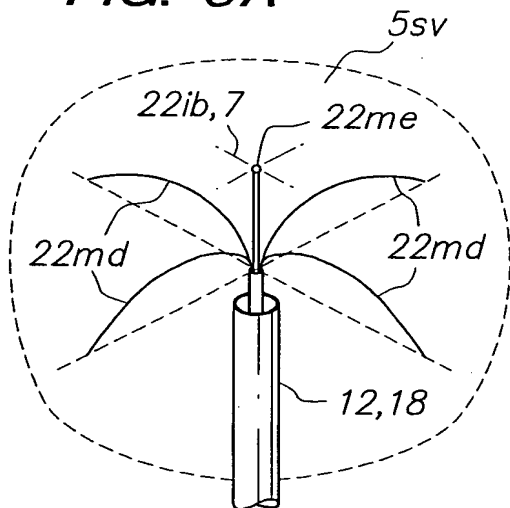


FIG. 8B

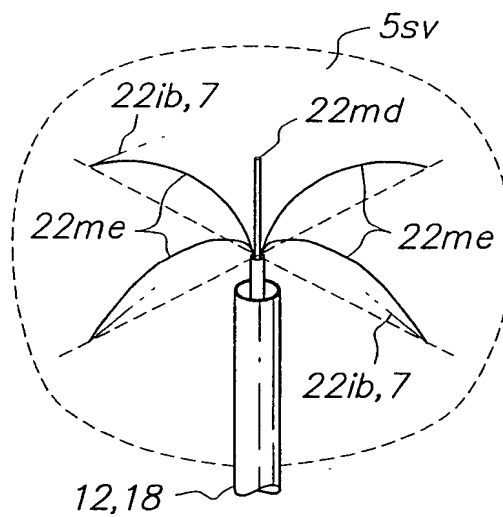


FIG. 8C

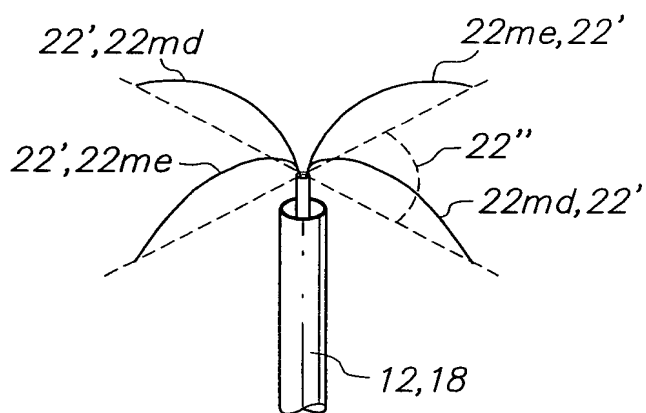
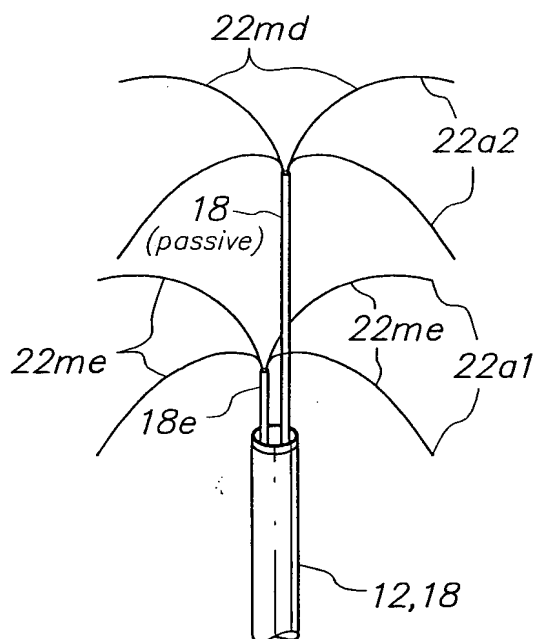


FIG. 8D



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1. The first step is to identify the problem or goal. This involves understanding the current situation and what needs to be achieved.

FIG. 9

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45"

45

43

5'

12dl

22m

18dd2

18e

5r,11

5''

5sv

22

18

5av

13

16

18,18e

12

10

19

20

17

FIG. 10

17

Laser

18, 18e, 12

22me

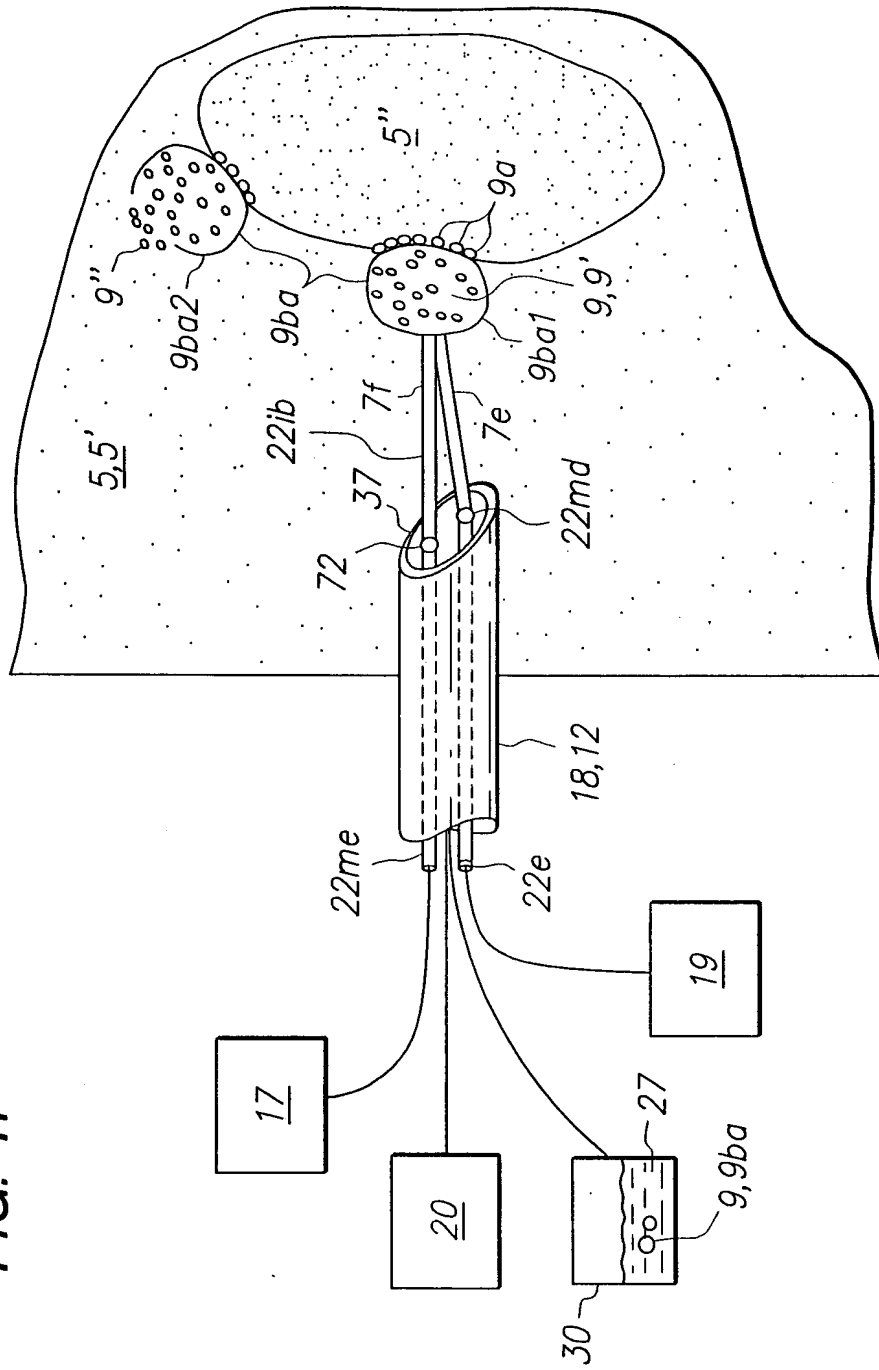
22ib', 7'

22md

22ib'', 7''

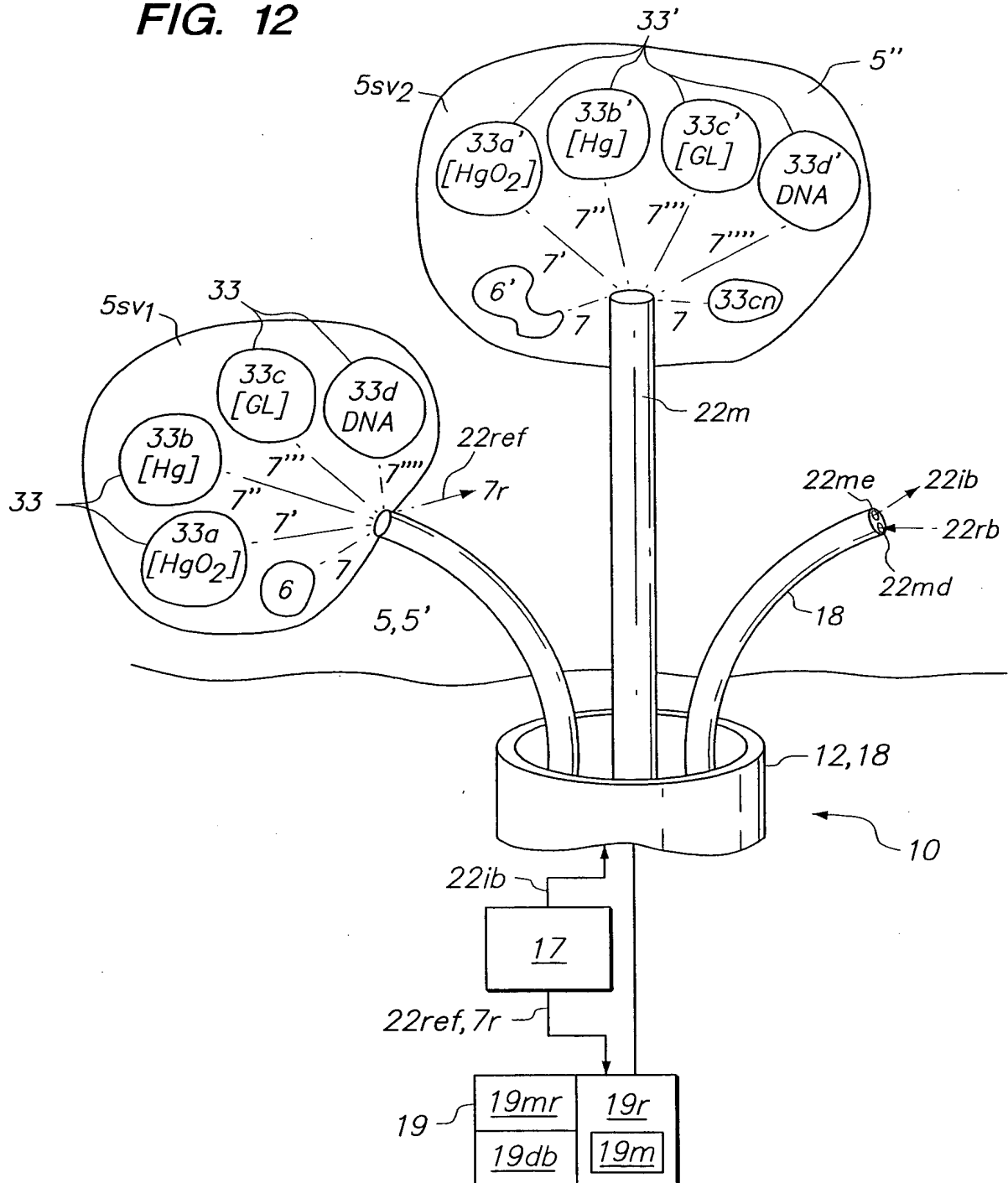
22me

FIG. 11



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FIG. 12



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FIG. 14A

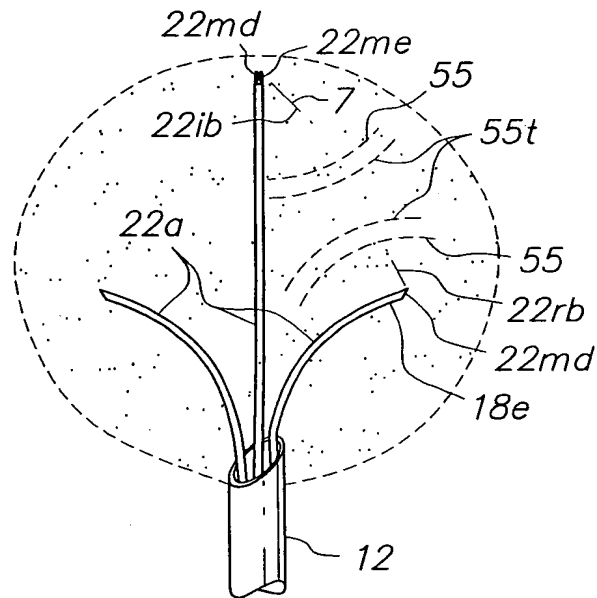


FIG. 14B

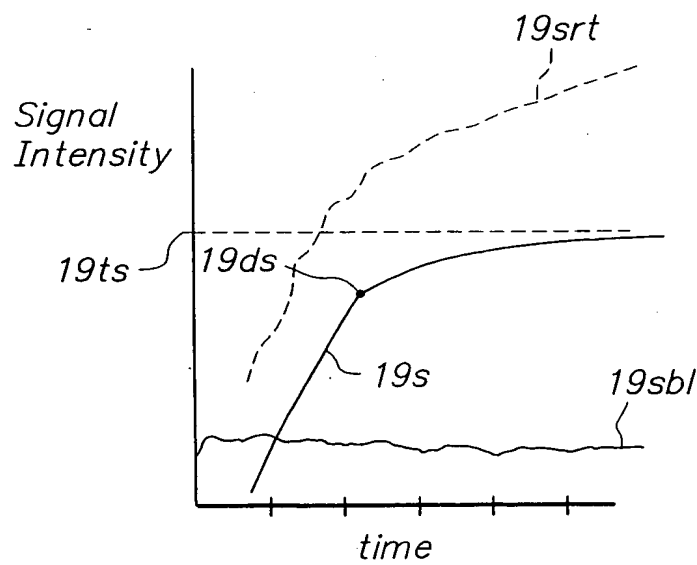


FIG. 15

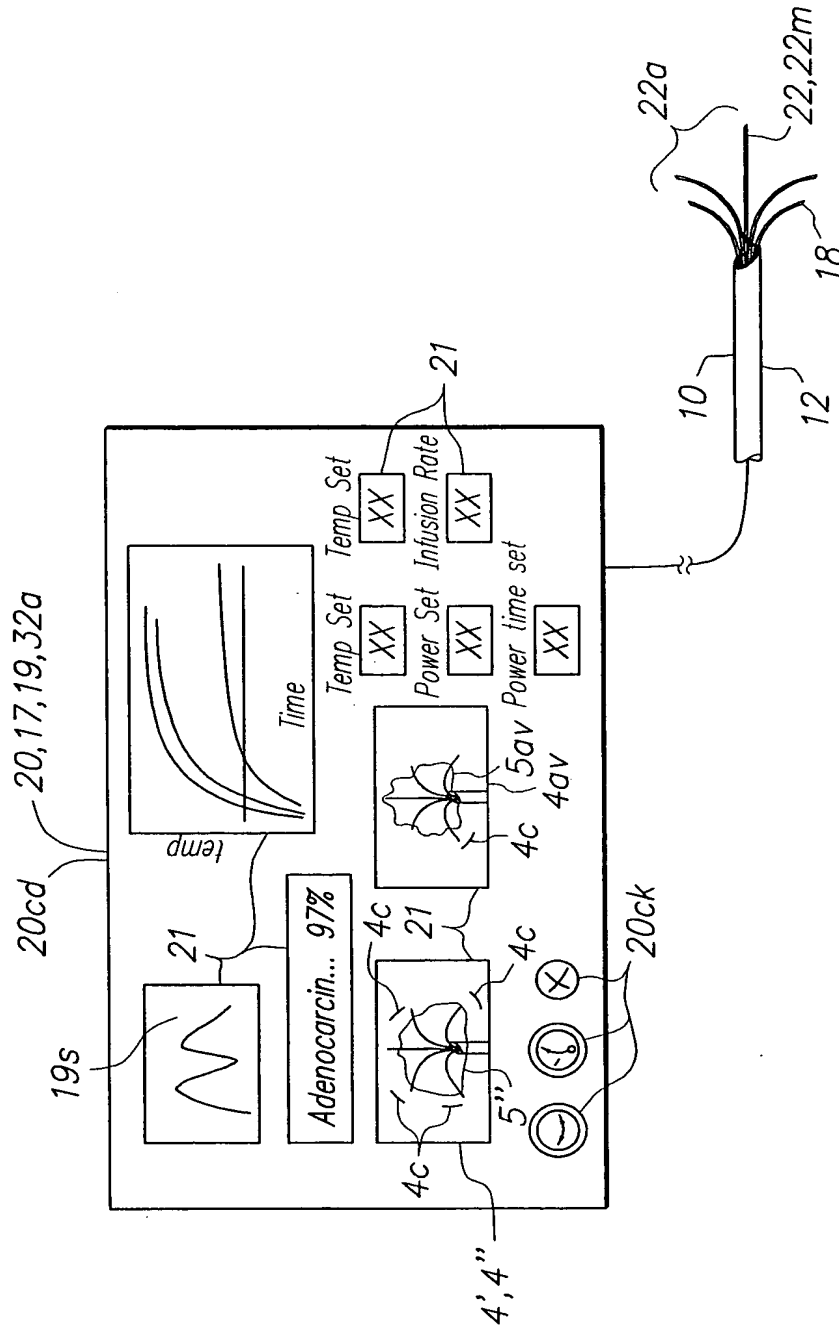


FIG. 16A

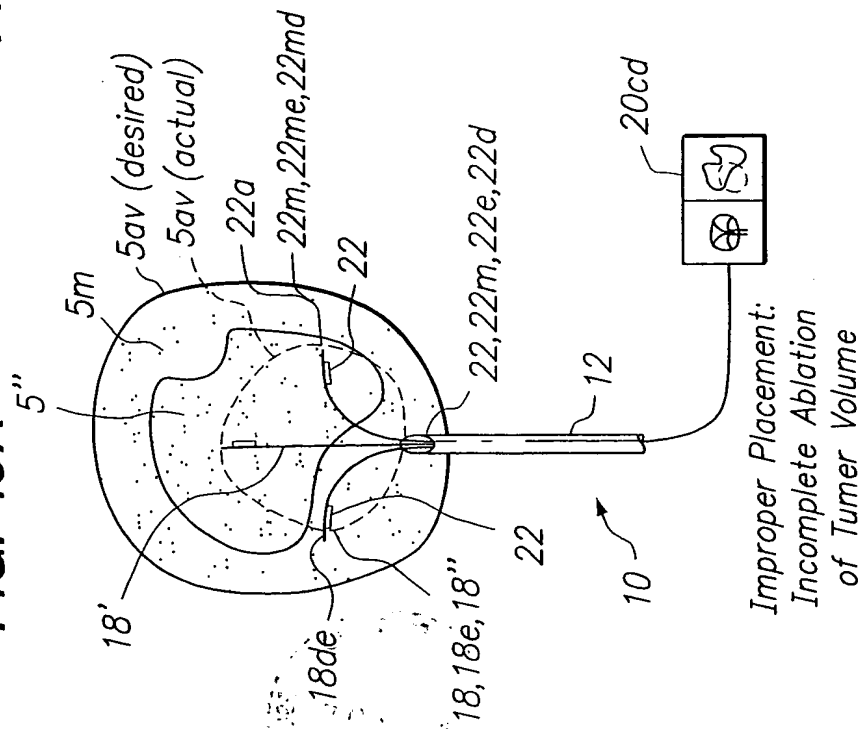


FIG. 16B

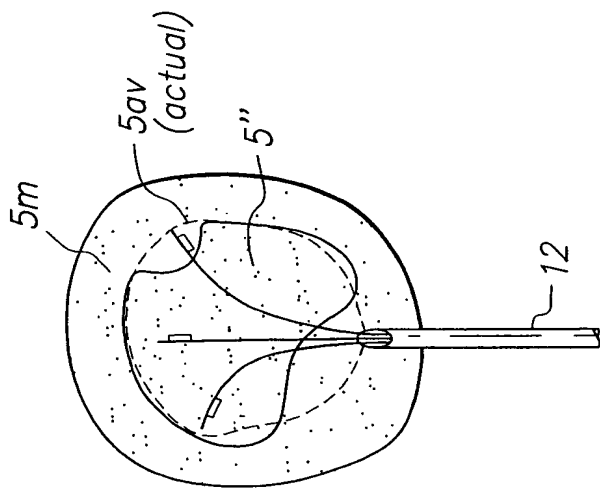


FIG. 16C

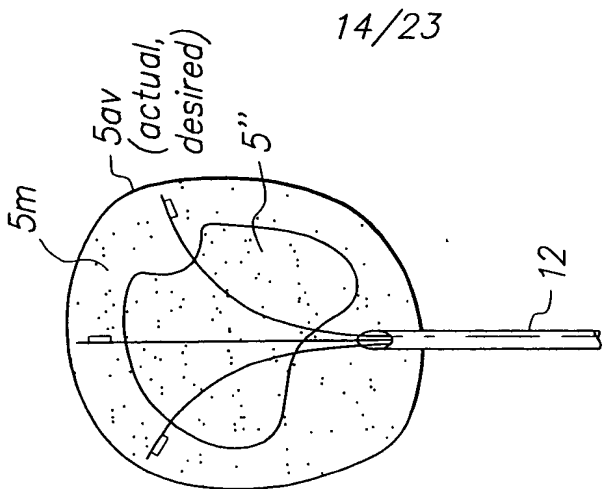
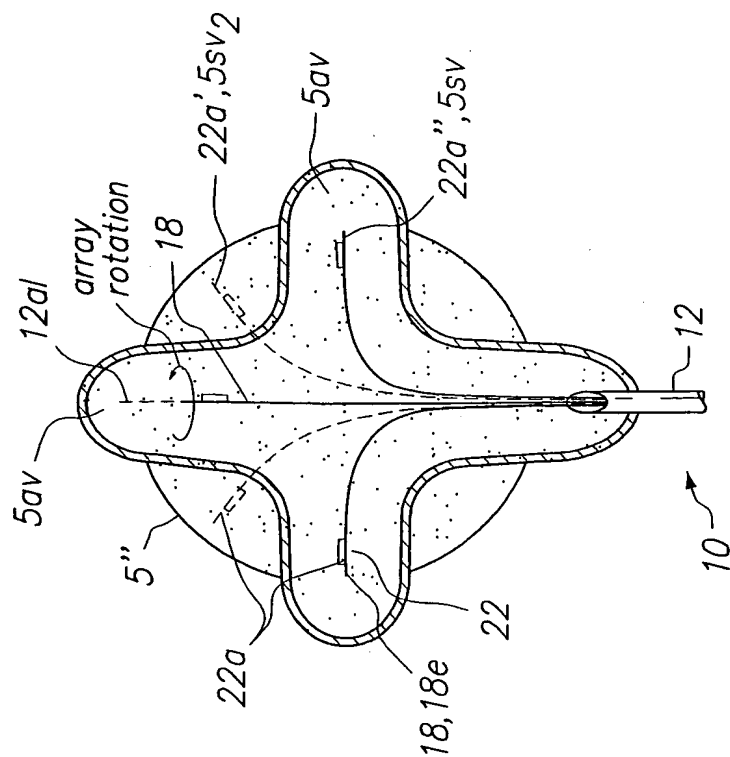
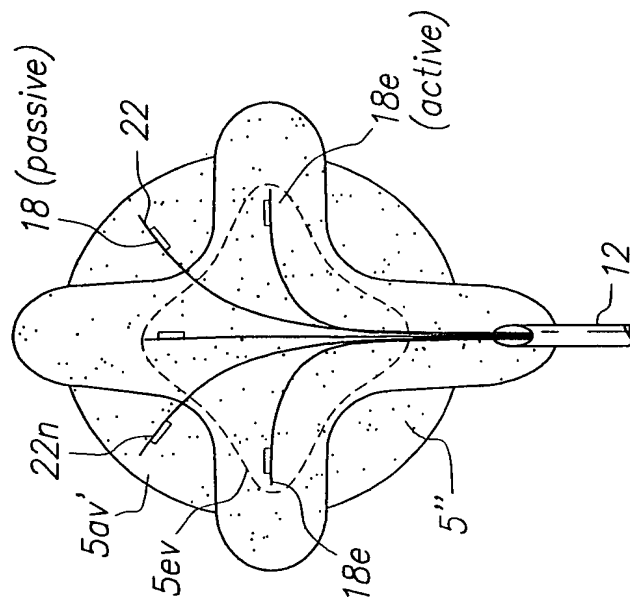


FIG. 17A



Detection of Incomplete Ablation
via rotation of electrode/sensor array

FIG. 17B



Detection of Incomplete Ablation
Deployment of passive Resilient Members 18
of Sensing Members 22m

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FIG. 18A

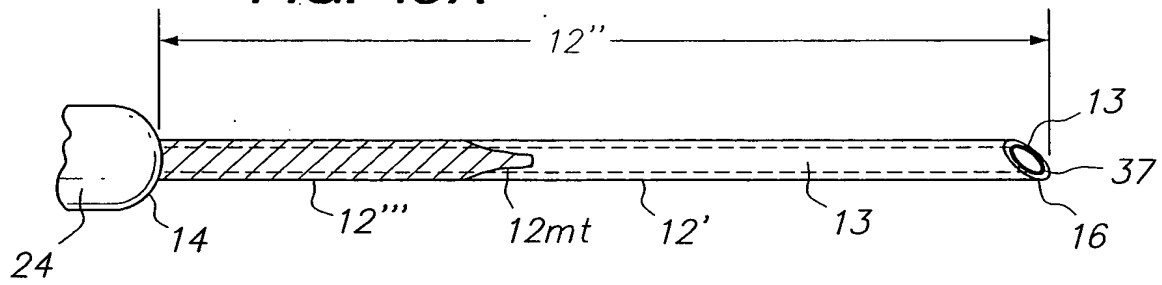


FIG. 18B

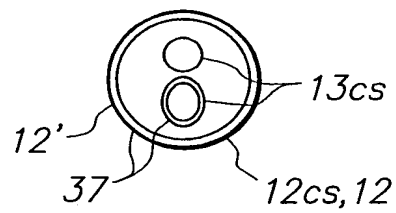


FIG. 18C

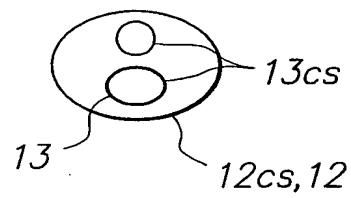
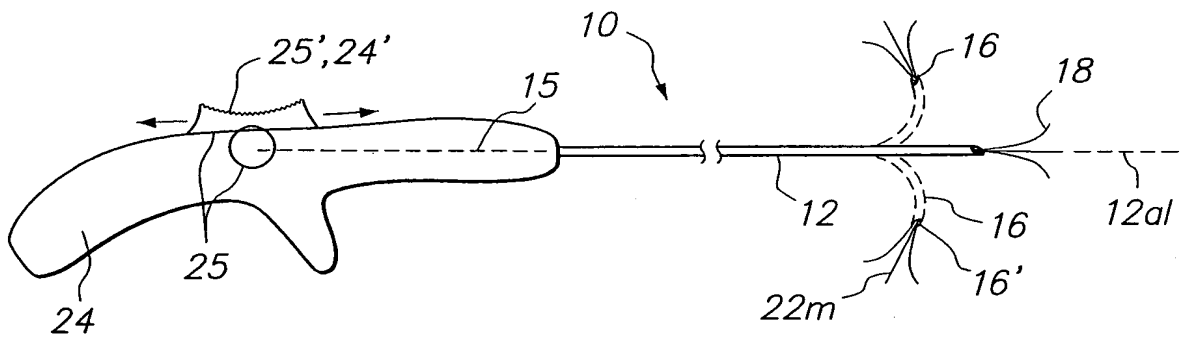


FIG. 19



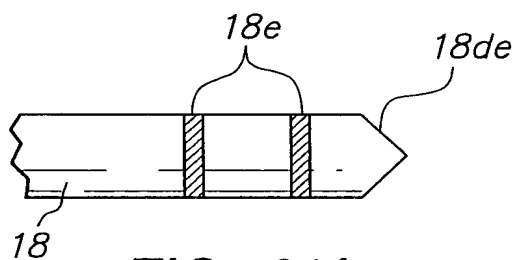


FIG. 21A

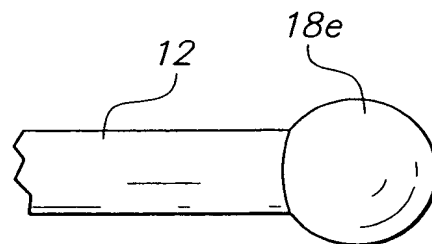


FIG. 21B

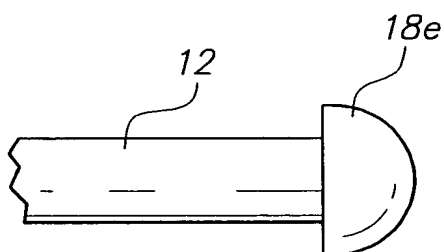


FIG. 21C

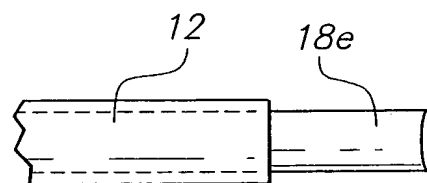


FIG. 21D

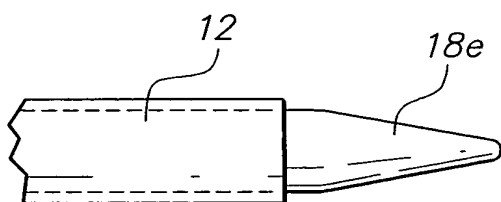


FIG. 21E

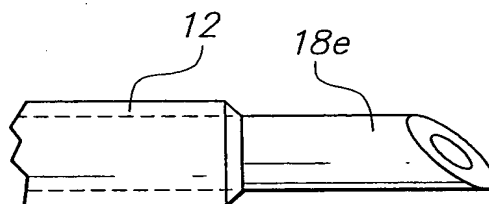


FIG. 21F

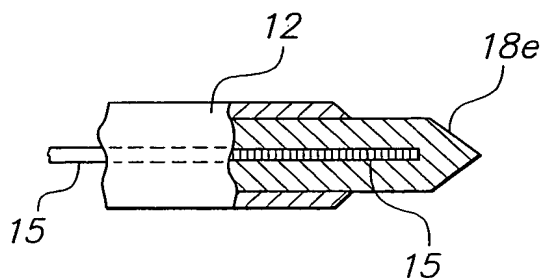


FIG. 21G

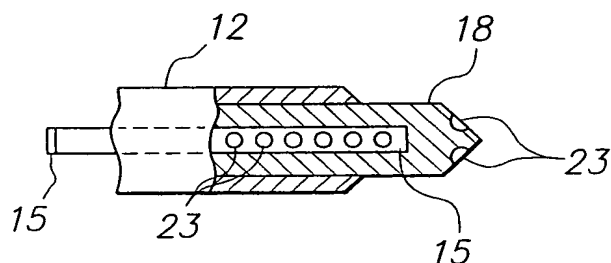
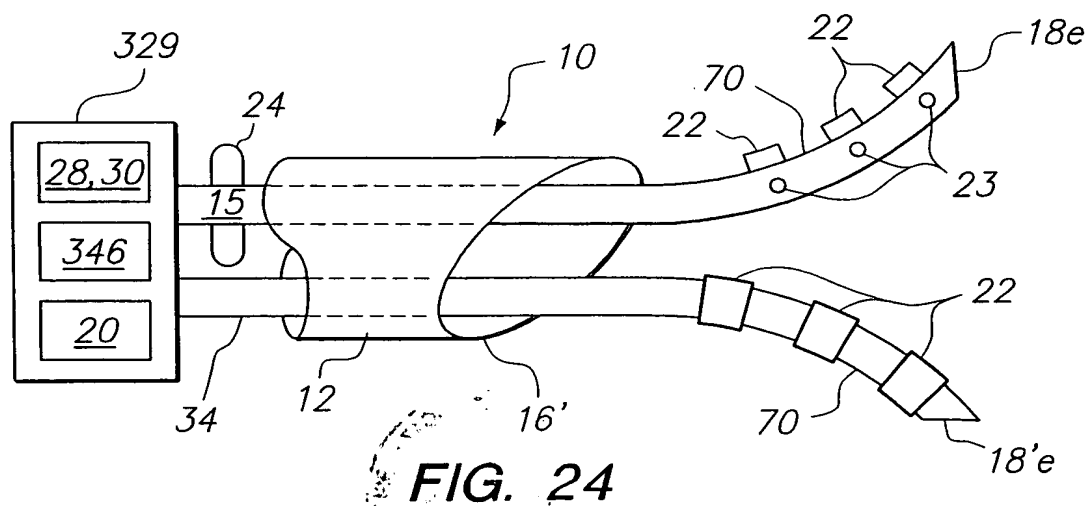
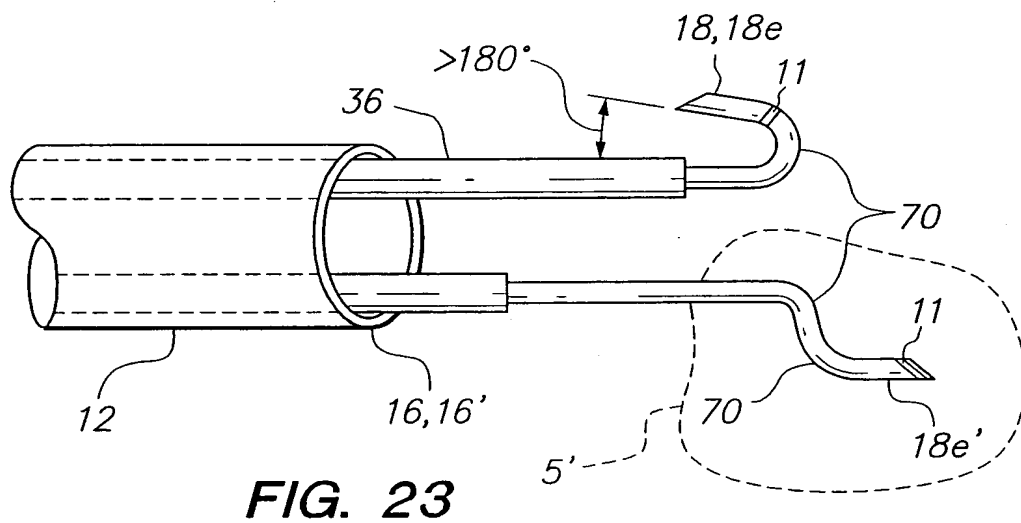
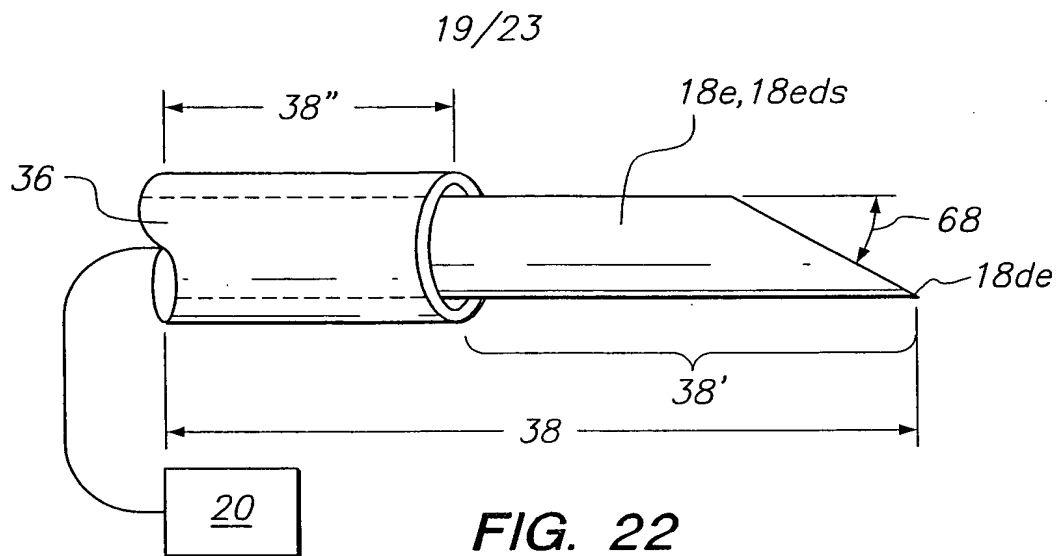
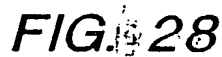


FIG. 21H

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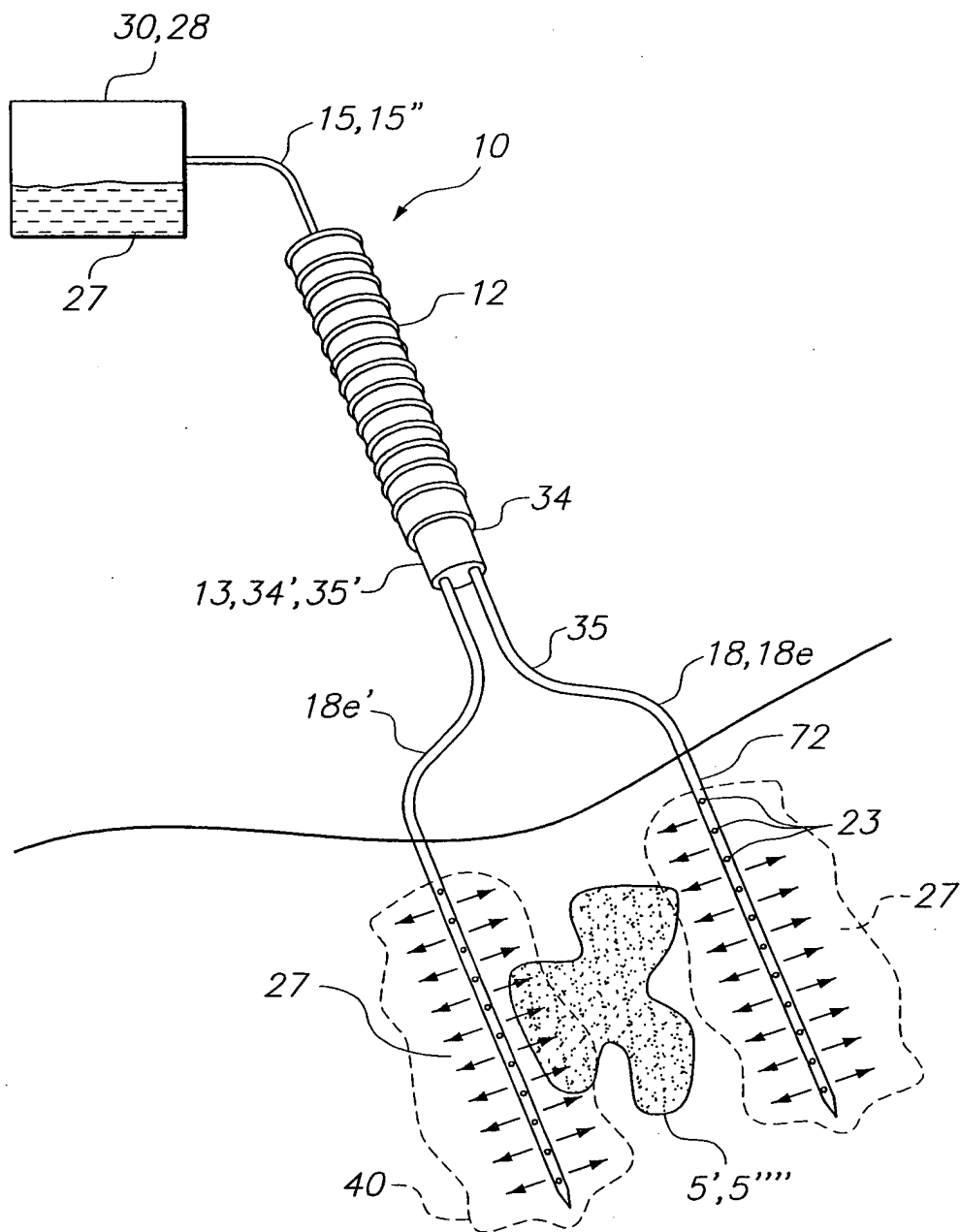


FIG. 29



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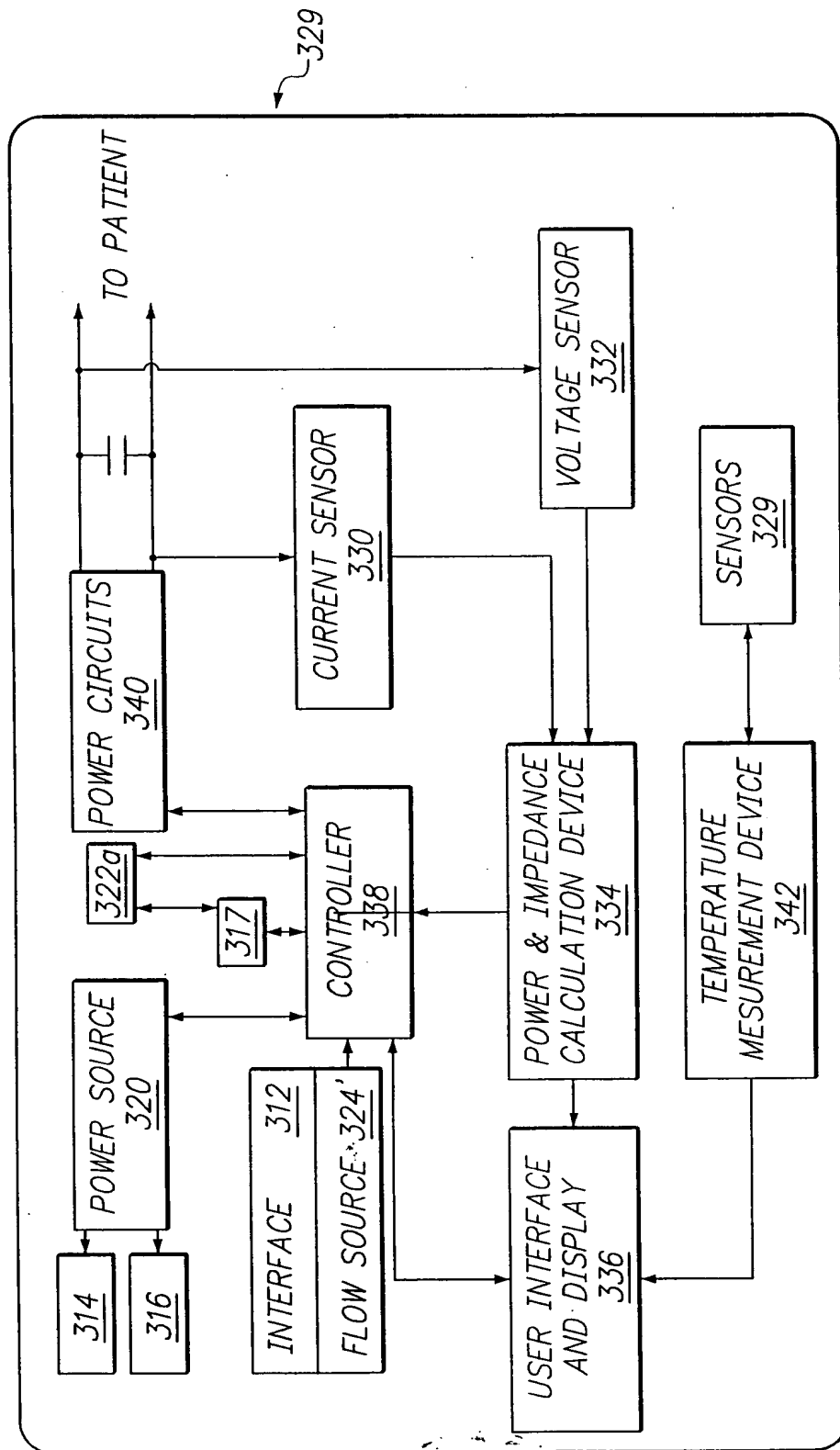


FIG. 30

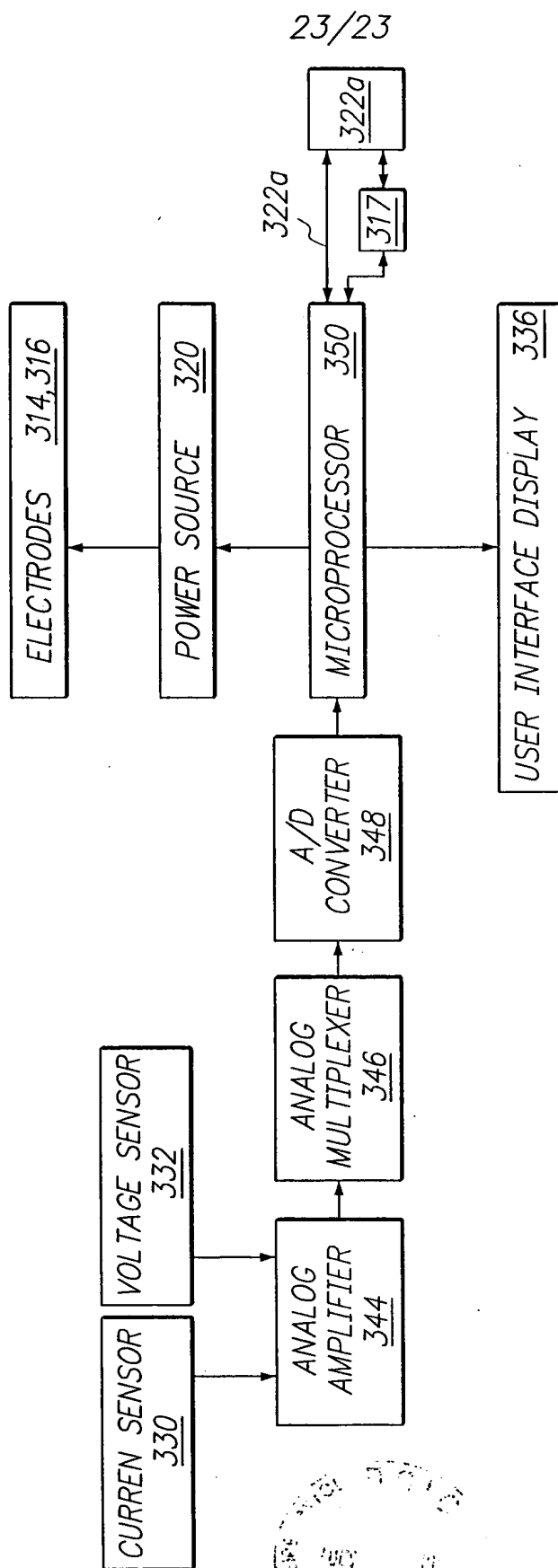


FIG. 31